

REMARKS

Claims 1-16 and 18-21 are pending herein. Claim 17 has been cancelled without prejudice or disclaimer. Claim 18 has been rewritten in independent form. Claims 2, 5, 6, 8 and 9 have been amended for clarification purposes only. Attached hereto as pages 11-13, pursuant to Rule 1.121(c)(1)(ii), is a marked-up version of the amended claims.

1. The objections to the specification and claims 2, 5-6, 8-16 and 18 are noted, but deemed moot in view of the substitute specification and rewritten claims submitted above.

2. Claims 1-21 were rejected under §102(b) over Otani. With respect to pending independent claims 1 and 8 (and claims depending therefrom), this rejection is respectfully traversed. To the extent that this rejection might be applied against amended claim 18, it is respectfully traversed.

With reference to Fig. 1 of the present application, pending independent claim 1 recites, among other things, that vibration element 12 is mounted on semiconductor integrated circuit chip 8, which is mounted on circuit board 6, by means of supporting member 9.

With reference to Figs. 2-4 of the present application, pending independent claim 8 recites, among other things, that lid 16 is secured to ceramic circuit board 18A to constitute a space into which vibration element 12 and vibration element supporting member 9 are installed.

With reference to Fig. 11 of the present application, pending independent claim 18 recites, among other things, that vibration element 12 is mounted on one surface (i.e., surface 6b) of circuit board 6 and semiconductor integrated circuit chip 8 is mounted on the other surface (i.e., surface 6c) of circuit board 6. The vibration element 12 and semiconductor integrated circuit chip 8 overlap one another when viewed in a direction in which the rotation axis extends (i.e., the Z-axis).

With reference to Fig. 1 of Otani, a sensing element 1a is positioned on silicon pedestal 1b, which is attached to hybrid integrated circuit (HIC) board 1.

With respect to pending independent claim 1, the PTO appears to be arguing that since Otani's circuit board is an HIC board, "circuit chips are provided on the board" (see page 4 of the Office Action). While Otani discloses that sensing element 1a is centrally positioned on HIC board 1, there is no disclosure or suggestion that sensing element 1a is mounted on any of the individual chip components (not shown in Otani's drawings) mounted on HIC board 1. Conversely, pending independent claim 1 recites that "said semiconductor integrated circuit chip is mounted on said circuit board..." and "said vibration element is mounted on said semiconductor integrated circuit chip...". Otani does not disclose this claimed structure. Nor is there evidence in Otani that skilled artisans would have reasonably expected that a vibration element is, or could even be for that matter, necessarily mounted on any of Otani's individual chip components, as claimed.

With respect to pending claims 8-21, the PTO alleges "the claims are commensurate in scope with claims 1-7 and are rejected for the same reasons..." (see page 4 of the Office Action). It is respectfully submitted that claims 8-21 **are not** commensurate in scope with claims 1-7. While an example of the angular velocity measuring apparatus recited in claims 1-7 is shown in Fig. 1, examples of the angular velocity measuring apparatuses recited in claims 8-16 and claims 7-20 are illustrated in Figs. 2-4 and Fig. 11, respectively. The differences between the apparatuses recited in each of these three claim sets will become clear upon reading the discussion below.

With respect to pending independent claim 8, and with reference to Figs. 1 and 2 of Otani, HIC board 1 is fitted in fitting grooves 2a of U-shaped resin package 2. A metallic cap 3 is fitted on resin package 2 to enclose HIC board 1 therein. As such, Otani discloses a separate, distinct package enclosing HIC board 1. In contrast to Otani's separate package, pending independent claim 8 recites that ceramic circuit board 18A itself and lid 16 define a space into which vibration element 12 and vibration element supporting member 9 are enclosed. Accordingly, even if Otani discloses a package enclosing HIC board 1, there is no disclosure or suggestion that HIC board 1 itself forms part of Otani's package, as is recited in

pending claim 8.

With respect to pending independent claim 18, as discussed above, the individual chip components mounted on Otani's HIC board 1 are not shown in Otani's drawings. Conversely, pending independent claim 18 recites that vibration element 12 and semiconductor integrated circuit chip 8 are mounted on opposite surfaces of circuit board 6 and overlap one another when viewed in a direction in which the rotation axis extends (i.e., Z-axis direction). Even if it is understood that circuit chips are present on a surface of Otani's HIC board 1, there is no disclosure in Otani that would have led skilled artisans to reasonably believe that circuit chips are mounted on opposite surfaces of HIC board 1, let alone that any of the individual chip components and sensing element 1a are positioned such that they overlap with one another in the rotation-axis direction, as claimed.

In view of all of the foregoing, reconsideration and withdrawal of the §102(b) rejection over Otani are respectfully requested.

3. Claims 1-21 were rejected under §102(b) over Asano et al. With respect to pending independent claims 1 and 8 (and claims depending therefrom), this rejection is respectfully traversed. To the extent that this rejection might be applied against amended claim 18, it is respectfully traversed.

With reference to Figs. 2 and 12 of Asano, an acceleration detecting element 2 is mounted on circuit board 3, which is positioned on metal base plate 5 and enclosed within metal cap 7. Circuit elements E are mounted on a surface of circuit board 3 that is opposite to the surface on which acceleration detecting element 2 is mounted .

With respect to pending independent claim 1, similar to Otani discussed above, acceleration detecting element 2 is not positioned on any of circuit elements E. Again, and in contrast to Asano, pending independent claim 1 recites that "said vibration element is mounted on said semiconductor integrated circuit chip..." and "said semiconductor integrated circuit chip is mounted on said circuit board...". There is no disclosure or suggestion in Asano that acceleration detecting element 2 is or should be positioned on any of the circuit

elements E, as claimed. This is especially true since Asano clearly shows that acceleration detecting element 2 is attached directly to circuit board 3 even though circuit elements E are also attached to circuit board 3.

With respect to pending independent claim 8, Asano discloses that a space S, into which acceleration detecting element 2 and circuit board 3 are each positioned, is defined by metal cap 7, which is secured to metal base plate 5. With reference to Fig. 2A of the the present application, for example, pending independent claim 8 recites that a lid 16 is secured to ceramic circuit board 18A to constitute a space, and vibration element 12 and vibration element supporting member 9 are installed within the space. Thus, ceramic circuit board 18A itself is part of the package defining the space that encloses vibration element 12 and vibration element supporting member 9. Similar to Otani discussed above, it is clear from the drawings in Asano that metal cap 7, which is part of a separate, distinct package, is not secured to any portion of ceramic board 3 to define a space into which acceleration detecting element 2 is provided.

With respect to pending independent claim 18, with reference to Figs. 2 and 12 of Asano, notwithstanding the fact that Asano discloses that circuit elements E can be mounted on opposite sides of circuit board 3, Asano does not disclose or suggest that acceleration detecting element 2 and any of circuit elements E actually overlap one another, as claimed. Figs. 2 and 12 of Asano are side views and show only that circuit elements E are positioned at some position on a surface of circuit board 3 that is opposite to the surface on which acceleration detecting element 2 is mounted. There is no disclosure or suggestion in Asano of the exact positioning of any of circuit elements E. For example, it is quite possible that acceleration detecting element 2 is centrally positioned on the upper surface of circuit board 3 (as shown in Fig. 3 of Asano) and circuit elements E are positioned on the opposite surface at outer, peripheral portions of circuit board 3 (i.e., positioned away from acceleration detecting element 2 when looking into the plane of the paper illustrating Figs. 2 and 3 of Asano), and do not overlap with any portion of acceleration detecting element 2. Accordingly, skilled

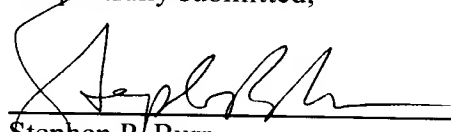
artisans could not know with any reasonable degree of certainty whether "said vibration element and said semiconductor integrated circuit chip are arranged to be overlapped with each other viewed in a direction in which said rotation axis extends," as recited in pending independent claim 18.

In view of all of the foregoing, reconsideration and withdrawal of the §102(b) rejection over Asano et al. are respectfully requested.

If the Examiner believes that contact with Applicants' attorney would be advantageous toward the disposition of this case, the Examiner is herein requested to call Applicants' attorney at the phone number noted below.

The Commissioner is hereby authorized to charge any additional fees associated with this communication or credit any overpayment to Deposit Account No. 50-1446.

Respectfully submitted,



Stephen P. Burr
Reg. No. 52,970

April 2, 2003

Date

SPB/SC/tlp

BURR & BROWN
P.O. Box 7068
Syracuse, NY 13261-7068

Customer No.: 025191
Telephone: (315) 233-8300
Facsimile: (315) 233-8320

2. (Amended) The angular velocity measuring apparatus according to claim 1, wherein said vibration element and said semiconductor integrated circuit chip are arranged to be overlapped with each other viewed in a direction in which said rotation axis extends.
5. (Amended) The angular velocity measuring apparatus according to claim 4, wherein said apparatus further comprises a can-package having a can-package base and a lid hermetically secured to the can-package base along ~~its periphery~~ a peripheral portion thereof to constitute a space, said vibration element, said supporting member, said circuit board and said semiconductor integrated circuit chip are installed within said space, and said circuit board is connected to conductor pins which extend into said space via through-holes formed in said can-package base.
6. (Amended) The angular velocity measuring apparatus according to claim 4, wherein said circuit board is formed by a ceramic circuit board having a base portion and a side wall portion defining an opening, and said apparatus further comprises a lid hermetically secured to said side wall portion of the ceramic circuit board to close said opening and to constitute a space, and said vibration element, said supporting member and said semiconductor integrated circuit chip are installed within said space.
8. (Amended) An angular velocity measuring apparatus for detecting a rotational angular velocity about a given rotation axis, comprising:
- a vibration element;
 - a vibration element supporting member for supporting said vibration element;

VERSION WITH MARKINGS TO SHOW CHANGES MADE
Amended claims

a semiconductor integrated circuit chip for controlling signals for the vibration element;

a ceramic circuit board for supporting said vibration element by means of said supporting member; and

a lid hermetically secured to said ceramic circuit board to constitute a space;
_____ wherein at least said vibration element and said vibration element supporting member are installed within said space.

9. (Amended) The angular velocity measuring apparatus according to claim 8, wherein said vibration element and said semiconductor integrated circuit chip are arranged to be overlapped with each other viewed in a direction in which said rotation axis extends.

18. (Amended) ~~The~~An angular velocity measuring apparatus according to claim 17, for detecting a rotational angular velocity about a given rotation axis, comprising:

_____ a vibration element;

_____ a vibration element supporting member for supporting said vibration element;

_____ a circuit board for supporting said vibration element by means of said supporting member;

_____ a semiconductor integrated circuit chip for controlling signals for the vibration element;

_____ a can-package having a can-package base and a can-package lid hermetically welded to the can-package base to constitute a space; and

_____ a plurality of conductor pins extending into said space through said can-package

VERSION WITH MARKINGS TO SHOW CHANGES MADE
Amended claims

base and electrically connected to said circuit board, wherein

said vibration element is mounted on one surface of said circuit board by means of
said vibration element supporting member, said semiconductor integrated circuit chip is
mounted on the other surface of the circuit board by bare-die-bonding and connected to
the circuit board by bonding wires, said circuit board and said conductor pins secured to
the can-package base are fixed by a silver paste, and whereinsaid vibration element and
said semiconductor integrated circuit chip are arranged to be overlapped with each other
viewed in a direction in which said rotation axis extends.

VERSION WITH MARKINGS TO SHOW CHANGES MADE
Amended claims



ANGULAR VELOCITY MEASURING APPARATUS

Background of the Invention

Field of the Invention

[0001] The present invention relates to an angular velocity measuring apparatus including a vibration type gyroscope.

Related Art Statements

[0002] Recently, in a vehicle control system utilizing a body rotation speed feedback system, a vibration type gyroscope has been proposed to be used as a rotation speed sensor. The vibration type gyroscope is an angular velocity sensor utilizing a Coriolis force which is produced by a rotation of a vibrating element. The vibrating element is vibrated electrically by supplying a driving signal thereto, and at the same time, a vibration induced by a Coriolis force is detected to measure an angular velocity of the rotational movement. In such a system, a direction in which driving wheels are directed is detected by a rotation angle of a steering wheel. At the same time, an actual rotation speed of a vehicle body is detected by the vibration type gyroscope. Then, the driving direction denoted by the steering wheel is compared with the direction obtained from the actual rotation speed to derive a difference, and wheel torque and driving angle are corrected in accordance with the thus detected difference to control the vehicle body stably.

[0003] In the vibration type gyroscope, the vibrating element is installed within a package or vessel such as can-package. The can-package is installed within a housing

together with a necessary circuit, and the housing is provided on the vehicle body. In this case, after securing a vibration element and a semiconductor integrated circuit chip to a supporting substrate, the substrate is secured to a base of the can-package by means of conductor pins.

[0004] For instant, in Japanese Patent Application Laid-open Publication Kokai 2000-9476, a vibration element of tuning fork type is fixed on a supporting substrate and the supporting substrate is installed within a package together with a swing-protection member which serves to prevent undesired swinging movement of the vibration element when unintentional vibration or impact is applied to the vibration element. In this manner, the vibration element can be protected against damage.

[0005] Since a space in which the vibration type gyroscopes is arranged in a vehicle is limited, it is required to reduce a surface area of the package as well as a height of the package. However, there has not been developed sufficiently effective measure for miniaturizing the package without affecting a performance of the gyroscope.

SummerySummary of the Invention

[0006] The present invention has for its object to provide an angular velocity measuring apparatus utilizing a vibration type gyroscope including a vibration element and a supporting substrate installed within a package, in which a size of the package can be miniaturized without affecting a performance of the vibration type gyroscope.

[0007] According to a first aspect of the invention, an angular velocity measuring apparatus for detecting a rotational angular velocity about a rotation axis, ~~comprises:~~
includes:

a vibration element;

a vibration element supporting member for supporting ~~said~~the vibration element;
a circuit board for supporting ~~said~~the vibration element by means of ~~said~~the
supporting member; and

a semiconductor integrated circuit chip for controlling signals for the vibration
element;

~~wherein said~~ The semiconductor integrated circuit chip is mounted on ~~said~~the circuit
board by flip-chip bonding, and ~~said~~the vibration element is mounted on ~~said~~the
semiconductor integrated circuit chip by means of ~~said~~the supporting member.

[0008] Upon manufacturing the angular velocity measuring apparatus having the
above mentioned unique structure, after mounting the semiconductor integrated circuit
onto the circuit board by means of the flip chip bonding, the vibration element is mounted
on a flat top surface of the semiconductor integrated circuit chip by means of the
supporting member. Then, a size of the angular velocity measuring apparatus can be
reduced greatly without affecting the vibration element, driving system for the vibration
element and a signal processing system for processing the signals supplied to and from the
vibration element.

[0009] In a preferable embodiment of the angular velocity measuring apparatus
according to the first aspect of the present invention, the vibration element is arranged to
extends on a given plane substantially perpendicular to a rotation axis of ~~the vibration of~~
the vibration element.

[0010] The arrangement of the vibration element along the given plane does not
strictly mean that the vibration element is formed to extend on a single surface, because
the vibration element has a finite thickness. Usually the vibration element may be

provided within a space having a height of about 1 mm on the given plane.

[0011] Furthermore, it is not always necessary that said given plane is set to be completely perpendicular to the rotation axis and may be inclined with respect to a plane perpendicular to the rotation axis due to a tolerance. Usually, said given plane may be inclined with respect to the real perpendicular plane by an angle not larger than 5°. Such a vibration element is generally called a laterally placed vibration element. The present invention can provide a remarkable improvement in reducing a size of the package for such a laterally placed vibration element.

[0012] In a preferable embodiment of the angular velocity measuring apparatus according to the first aspect of the invention, the semiconductor integrated circuit chip is arranged to extend substantially in parallel with the vibration element. In this case, the vibration element and semiconductor integrated circuit chip are preferably overlapped with each other viewed in a direction of the rotation axis. Then, a height and a lateral dimension of the can-package can be effectively reduced.

[0013] According to the invention, any kind of the semiconductor integrated circuit chip for controlling a driving signal supplied to the vibration element and a detection signal generated from the vibration element may be used. Particularly, it is preferable to use ASIC (Application Specified Integrated Circuit).

[0014] When the semiconductor integrated circuit chip is mounted on the circuit board by the flip chip bonding and the vibration element is mounted on the semiconductor integrated circuit chip by means of the supporting member, the thus assembled vibration element, supporting member, circuit board and semiconductor integrated circuit chip may be accommodated within a can-package.

[0015] According to a second aspect of the invention, an angular velocity measuring apparatus for detecting a rotational angular velocity about a given rotation axis, ~~comprises:~~includes:

a vibration element;

a vibration element supporting member for supporting ~~said~~the vibration element;

a semiconductor integrated circuit chip for controlling signals for the vibration element;

a ceramic circuit board for supporting ~~said~~the vibration element by means of ~~said~~the supporting member; and

a lid hermetically secured to ~~said~~the ceramic circuit board to constitute a space; wherein at least ~~said~~the vibration element and vibration element supporting member are installed within ~~said~~the space.

[0016] In this manner, when the vibration element is mounted on the ceramic circuit board by means of the vibration element supporting member, a standoff from a mother board which is required in the known can-package can be dispensed with, and therefore a height of the package after installing the vibration element can be further reduced. Furthermore, in the can-package, conductor pins have to be inserted into through-holes formed in a base of the can-package and then the conductor pins have to be soldered to the circuit board. In case of using the ceramic circuit board according to the second aspect of the present invention, it is no more necessary to use the conductor pins, and the semiconductor integrated circuit chip can be connected to an external circuit by soldering conductors to contact lands provided on a rear surface of the ceramic circuit board. Therefore, undesired damage and breakage of conductor pins can be avoided. When

impact is applied to the package from the external, the conductor pins might be twisted and an error signal might be generated. According to the second aspect of the invention, the generation of such an error signal can be also suppressed.

[0017] According to a third aspect of the invention, an angular velocity measuring apparatus for detecting a rotational angular velocity about a given rotation axis, ~~comprises:~~includes:

- a vibration element;
 - a vibration element supporting member for supporting ~~said~~the vibration element;
 - a circuit board for supporting ~~said~~the vibration element by means of ~~said~~the supporting member;
 - a semiconductor integrated circuit chip for controlling signals for the vibration element;
 - a can-package having a can-package base and a can-package lid hermetically welded to the can-package base to constitute a space; and
 - a plurality of conductor pins extending into ~~said~~the space through ~~said~~the can-package base and electrically connected to ~~said~~the circuit board;
- _____ wherein ~~said~~the vibration element is mounted on one surface of ~~said~~the circuit board by means of ~~said~~the vibration element supporting member, ~~said~~the semiconductor integrated circuit chip is mounted on the other surface of the circuit board by bare-die-bonding and is connected to the circuit board by bonding wires, ~~said~~the circuit board and ~~said~~the conductor pins secured to the can-package base are fixed by a silver paste.

[0018] Since the semiconductor integrated circuit chip is mounted on the rear surface of the circuit board by means of the bare-die-bonding and is connected to the circuit board

by bonding wires, the potting process for protecting the semiconductor integrated circuit chip and bonding wires is no more necessary. Furthermore, since the semiconductor integrated circuit chip is provided between the circuit board and the base of the can-package, the semiconductor integrated circuit chip can be effectively prevented from being damaged by unintentional impact during a manufacturing process prior to welding the lid to the can-package in an air-tight manner. Moreover, since the circuit board is connected to the conductor pins by means of the silver paste, a washing process which is required in the case of soldering may be dispensed with.

Brief Description of the drawings

Fig. 1 is a cross sectional view showing schematically an embodiment of the angular velocity measuring apparatus according to the first aspect of the invention;

Figs. 2A and 2B are plan and cross sectional views illustrating an embodiment of the angular velocity measuring apparatus according to the second aspect of the invention;

Fig. 3 is a cross sectional view depicting another embodiment of the angular velocity measuring apparatus according to the second aspect of the invention;

Fig. 4 is a cross sectional view showing another embodiment of the angular velocity measuring apparatus according to the first aspect of the invention;

Figs. 5-10 are perspective views illustrating several embodiments of the ceramic circuit board used in the embodiments according to the invention; and

Fig. 11 is a cross sectional view representing an embodiment of the angular velocity measuring apparatus according to the third aspect of the invention.

Detailed Description of the Invention Preferred Embodiments

**VERSION WITH MARKINGS TO SHOW CHANGES MADE
Appendix B**

[0019] ~~Now~~ Several embodiments of the angular velocity measuring apparatus according to the invention will be explained with reference to the accompanying drawings.

[0020] Fig. 1 is a cross sectional view showing an embodiment of the angular velocity measuring apparatus according to the first aspect of the invention. Upon manufacturing the angular velocity apparatus 1A, at first, chip components 7B are mounted on a surface 6b of a circuit board 6, and further a semiconductor integrated circuit chip 8 is mounted on the surface 6b of the circuit board 6 at a central portion thereof by means of the flip-chip bonding. Chip components 7A are mounted on surface 6c of circuit board 6. The flip-chip bonding is a well known bonding technique, in which the semiconductor integrated circuit chip 8 is first placed on the surface of the circuit board 6 and then a space between the chip 8 and circuit board surface is filled with plastics.

[0021] Next, the circuit board 6 is supported by a can-package base 3. That is to say, conductor pins 5 are inserted into through-holes 3b formed in the can-package base 3 and then are inserted into through-holes 6a formed in the circuit board 6. ~~Nest~~Next, the conductor pins 5 are secured to the circuit board 6 by soldering.

[0022] Then, a vibration element 12 is provided on a flat top surface of the semiconductor integrated circuit chip 8 by means of a supporting member 9. The supporting member 9 includes a support rod 10 made of a metal and cemented onto the top surface of the chip 8, and an adhesive layer 11 by means of which the support rod 10 is cemented onto a rear surface 12b of the vibration element 12 by means of an adhesive. One ends of each of wires 13 ~~are~~is connected to a front surface 12a of the vibration element 12 and the other ends of each of wires 13 ~~are~~is connected to a front surface 6a of the circuit board 6. Finally, a lid 2 is secured to a flange 3a of the can-package base 3 by

resistance welding. In Fig. 1, a welded portion is denoted by a reference numeral 4.

[0023] In the present embodiment, the vibration element 12 extends substantially in parallel with an X-Y plane, and a rotation axis of the vibration element extends in a Z direction which is perpendicular to the X-Y plane. An angular velocity of a rotational movement ω about the rotation axis extending in the Z direction is detected.

[0024] Fig. 2 is a cross sectional view illustrating a package used in an embodiment of the angular velocity measuring apparatus according to the second aspect of the invention.

A package 15 includes a ceramic circuit board 18A, and a vibration element 12 is provided on an inner surface 18e of a flat plate portion 18c of the ceramic circuit board 18A by means of a supporting member 9. An outer surface 18d of the flat plate portion 18c is formed flat. The ceramic circuit board 18A further includes a side wall portion 18b formed along a periphery of the flat plate portion 18c. An opening defined by the side wall portion 18b is covered with a lid 16 to constitute the package 15. The vibration element 12 and supporting member 9 are installed within an inner space 17 of the package 15. An inner surface 18e of the flat plate portion 18c of the ceramic circuit board 18A facing the vibration element 12 includes step portions 18a which extend from the periphery of the flat plate portion 18c. One ends of each of the bonding wires 13 ~~are~~is connected to the front surface 12a of the vibration element 12 and the other ends of each of the bonding wires 13 ~~are~~is connected to contact lands provided on the step portions 18a.

[0025] As explained above, in the present embodiment, the ceramic circuit board 18A ~~have~~has the step portions 18a formed in the inner surface of the ceramic circuit board 18A to protrude toward the vibration element 12 and the bonding wires are connected to the lands provided on top surfaces of the step portions 18a, whose level is higher than the

inner surface 18e of the flat plate portion 18c, and therefore a difference in the levels of the ends of the bonding wires 13 can be reduced. This results in ~~that~~ a height of the package 15 ~~can be~~ being reduced. Moreover, a length of the bonding wires 13 can be also reduced.

[0026] Fig. 2B shows an embodiment of the angular velocity measuring apparatus using the package 15 shown in Fig. 2A. In the present embodiment, the package 15 in which the vibration element 12 and supporting member 9 are installed is coupled with a fitting member 19 such that a space 20 is formed between the package and the fitting member, and a semiconductor integrated circuit chip 28 is installed within this space.

[0027] The fitting member 19 formed by a ceramic circuit board includes a circuit portion 19c. On an outer surface 19e of the circuit portion 19c of the fitting member 19 are provided chip components 7A, and on an inner surface 19d of the circuit portion 19c are arranged chip components 7B and the semiconductor integrated circuit chip 28. The semiconductor integrated circuit chip 28 is mounted on the inner surface 19d of the circuit portion 19c of the fitting member 19 by means of the flip-chip bonding. The semiconductor integrated circuit chip 28 is connected to contact lands of the circuit portion 19c by means of bonding wires 13. The fitting member 19 further comprises peripheral side wall portions 19a and 19b, and the package 15 is secured to the peripheral side wall portion 19a to form the space 20. As stated above, the semiconductor integrated circuit chip 28 is arranged within this space 20. It should be noted that the ceramic circuit board 18A is also electrically connected to the fitting member 19 by means of electrodes provided on the surface 18d of the flat plate portion 18c of the ceramic circuit board 18A and via-holes embedded in the side wall portion 19a.

[0028] In the present embodiment, a part of the ceramic circuit board on which the semiconductor integrated circuit chip 28 is mounted and a part of the ceramic circuit board supporting the vibration element 12 are separated from each other, and therefore a limitation in designing the circuit structure can be mitigated.

[0029] In the present embodiment, the semiconductor integrated circuit chip 28 is overlapped with the vibration element 12 viewed in the Z direction. Therefore, a lateral size of the whole package can be reduced. In the present embodiment, the semiconductor integrated circuit chip 28 is secured to the circuit portion 19c of the fitting member 19 by the flip-chip bonding, but it may be fixed by any other bonding method.

[0030] In an embodiment of the angular velocity measuring apparatus 1C shown in Fig. 3, a semiconductor integrated circuit chip 28 is provided on a surface 18d of a flat plate portion 18c of a ceramic circuit board 18A, said surface being opposite to a lid 16. Chip components 7A and 7B are secured to the either surfaces 18d and 18e of the flat plate portion 18c. Then, a height of the whole package can be further reduced. As shown in Fig. 3, the ceramic circuit board 18A further includes a peripheral side wall 18f extending from the periphery of the flat plate portion 18c in a direction opposite to the lid 16. Also in this embodiment, the semiconductor integrated circuit chip 28 is fixed to the surface 18d of the flat plate portion 18c by the flip-chip bonding, but it may be secured by any other bonding method.

[0031] Fig. 4 is a cross sectional view depicting another embodiment of the angular velocity measuring apparatus 1D according to the first aspect of the invention. A semiconductor integrated circuit chip 8 is fixed by the flip-chip bonding onto a surface 18e of a flat plate portion 18c of a fitting member constituting a ceramic circuit board 18B, and

a vibration element 12 is provided on a flat top surface of the semiconductor integrated circuit chip 8 by means of a supporting member 9. That is to say, the semiconductor integrated circuit chip 8 and vibration element 12 are installed within a space 17 formed by the ceramic circuit board 18B and a lid 16 hermetically secured to an opening of the ceramic circuit board 18B.

[0032] In the present embodiment, like as the previous embodiment shown in Fig. 1, a height of the whole package can be reduced and a surface area of the flat plate portion 18c can be decreased.

[0033] Figs. 5-10 are perspective views illustrating several embodiments of the ceramic circuit board ~~while with~~ the lid 16 ~~is being~~ removed. Fig. 5 shows the ceramic circuit board 18A used in the embodiment shown in Fig. 2. In this embodiment, there are formed four step portions 18a at respective corners. Fig. 6 depicts the ceramic circuit board 18B used in the embodiment illustrated in Fig. 4. In this case, there is not provided a step portion. Furthermore, it is preferable that a driving vibration mode Vd of the vibration element and a detecting vibration mode Vt are in a-substantially the same plane.

[0034] In a ceramic circuit board 18C depicted in Fig. 7, there are formed eight step portions 18f. Such step portions 18f may be obtained by dividing each of the four step portions 18a shown in Fig. 5 into two narrow step portions.

[0035] In a ceramic circuit board 18D shown in Fig. 8, semicircular step portions 18g are provided, and in a ceramic circuit board 18E illustrated in Fig. 9, there are formed rectangular step portions 18h each having an enlarged tip portion. In a ceramic circuit board 18F shown in Fig. 10, there are provided four rectangular step portions 18j each including a narrowed tip.

[0036] Fig. 11 is a cross sectional view showing an embodiment of the angular velocity measuring apparatus according to the third aspect of the invention. Upon manufacturing the apparatus 1E of the present embodiment, at first, chip components 7B are secured to a front surface 6b of a circuit board 6 and chip components 7A are provided on a rear surface 6c of the circuit board 6. A semiconductor integrated circuit chip 8 is secured to the surface 6c of the circuit board 6 by means of the bare die-bonding, and wires 13 are provided by the wire bonding. In the embodiment shown in Fig. 1, the front surface of the semiconductor integrated circuit chip 8 is brought into contact with the surface of the circuit board 6, and then the potting is performed to cover an exposed rear surface of the semiconductor chip 8 with plastics. However, in the present embodiment, such a potting treatment is dispensed with.

[0037] Next, conductor pins 5 secured to a can-package base 3 are inserted into through holes 6a formed in the circuit board 6 and the conductor pins 5 are connected to the circuit board 6 by means of a silver paste. By connecting the conductor pins 5 and circuit board 6 with a silver paste instead of soldering, a washing process can be dispensed with. In this manner, in the present embodiment, since the potting process as well as the washing process are dispensed with, throughput can be improved.

[0038] Next, a vibration element 12 is secured to the front surface 6b of the circuit board 6 at a central portion of the circuit board by means of a supporting member 9 including a metal support rod 10 and an adhesive layer 11. The vibration element 12 is connected by bonding wires 13 to the circuit board 6. Finally, a lid 2 of the can-package is secured to a flange 3a of the can-package base 3 with the resistance welding. A welding portion is denoted by a reference numeral 4 in Fig. 11.

[0039] In this manner, the semiconductor integrated circuit chip 8 and vibration element 12 are arranged to be overlapped with each other, and thus a lateral dimension of the angular velocity measuring apparatus 1E can be reduced like as the previous embodiments. Moreover, as compared with the embodiment illustrated in Fig. 1, the space between the circuit board 6 and the can-package base 3 is utilized effectively, and therefore a height of the angular velocity measuring apparatus 1E can be further reduced.

[0040] The present invention is not limited to the embodiments explained so far, but many alternations and modifications within the scope of the claims may be conceived by a person skilled in the art ~~within a scope of claims~~. For instance, instead of the can-package, use may be made of a vessel consisting of a flat glass epoxy substrate and a box-like member formed by folding a metal plate and secured to the glass epoxy substrate by soldering. A means for driving the vibration element and a means for detecting a detection signal from the vibration element may be any conventional means widely used in the vibration type gyroscopes. When the vibration element is made of a piezoelectric material, driving electrodes and detection electrodes are provided on the element. As a piezoelectric material, not only a piezoelectric single crystal, but also a piezoelectric ceramics such as PZT may be used. When the vibration element is made of ~~an~~ identity elastic metal or alloy, driving electrodes and detection electrodes made of piezoelectric ceramics may be applied on the element.

[0041] It should be noted that the vibration element may be supported by any suitable method such as cementing with adhesive agent or viscoelastic agent, mechanical fixing with clamps, welding, and solid-phase diffusion. It is preferable to secure the vibration element with the aid of adhesive agent in order to attain a high detection sensitivity.

[0042] The adhesive layer 11 for cementing the support rod 10 of the vibration element supporting member 9 to the vibration element 12 may be made of any adhesive material selected from a synthetic rubber adhesive agent such as silicone adhesive agent and urethane rubber adhesive agent and a synthetic resin adhesive agent such as epoxy adhesive agent and polyimide adhesive agent. In this case, it is preferable that a dynamic modulus of elasticity of the adhesive agent is not larger than one hundredth of that of the vibration element. Then, the adhesive agent could not affect the vibrating condition. Practically, when the vibration element is made of piezoelectric single crystal or piezoelectric ceramics or identity elastic metal, a dynamic modulus of elasticity of the adhesive agent is preferably 10^6 - 10^8 Pa.

[0043] In order to fix the vibration element firmly, the adhesive layer 11 preferably has a thickness not larger than 1 mm, particularly not larger than 0.4 mm. On the other hand, in order to suppress a change in Q value of the vibration of the vibration element over an operation temperature range and to increase a detection sensitivity of the vibration, it is preferable that a thickness of the adhesive layer 11 is not smaller than 0.05 mm, particularly not smaller than 0.1 mm.

[0044] In order to make the Q value of the vibration over an operation temperature range (usually -30°C - $+85^{\circ}\text{C}$, particularly -40°C - $+85^{\circ}\text{C}$) larger and constant, $\tan \delta$ of the adhesive layer 11 is ~~preferable~~preferably not larger than 0.05. An upper limit of $\tan \delta$ of the adhesive layer 11 is not set and may be zero. Within the operation temperature range, a ratio of a maximum value of $\tan \delta$ of the adhesive layer 11 with respect to a minimum value is preferably not larger than 3. In order to make Q value of the vibration constant, a specific gravity of the adhesive layer 11 is preferably not larger than 1.1. To

this end, an amount of filler contained in the adhesive layer may be not larger than 7 weight %.

[0045] According to the invention, a temperature of the vibration element can be controlled by utilizing heat generated by the semiconductor integrated circuit chip. When an ambient temperature changes over a wide range such as $-40^{\circ}\text{C} - +85^{\circ}\text{C}$, an ambient temperature of the vibration element can be preferably adjusted within a smaller temperature range such as $0^{\circ}\text{C} - +85^{\circ}\text{C}$, particularly $+25^{\circ}\text{C} - +85^{\circ}\text{C}$ by utilizing the heat generated by the semiconductor integrated circuit chip. Furthermore, by using Peltier element in combination with the heat generated by the semiconductor integrated element, an ambient temperature of the vibration element can be controlled to a constant temperature within a range of $0^{\circ}\text{C} - +85^{\circ}\text{C}$, particularly $+25^{\circ}\text{C} - +85^{\circ}\text{C}$ or can be maintained at a constant temperature not higher than $+45^{\circ}\text{C}$.

[0046] As explained above in detail, in the angular velocity measuring apparatus according to the invention, a package accommodating the vibration element, circuit board and semiconductor integrated circuit chip can be minimized.